

Abstract

A device and a method for notifying the driver of a motor vehicle, equipped with an adaptive distance and speed controller, by activating a takeover prompt, informing the driver that the vehicle is coming critically close to a target object. The takeover prompt is activated and deactivated as a function of a fixed minimum distance between the distance- and speed-controlled vehicle and the target object and/or a relative speed-dependent minimum distance between the distance- and speed-controlled vehicle and a target object and/or a maximum vehicle deceleration producible by the distance and speed controller.

10 (Figure 1)